



MEMS Applications in Propulsion: Problems and Possibilities

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Brief History

- MEMS (Micro electrical mechanical systems) or Microsystems (in use in Europe) is based on the use of microelectronic fabrication methods to make very small mechanical devices.
- MEMS devices began to emerge in the early 1980's and most early successes were sensors.
- Application areas are diverse and include sensors, fluid control and manipulation, optics, displays, printing, electrical switching, chemical analysis, biochemical fluid processing, precise motion control and data storage.





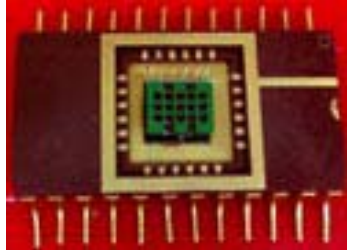
Propulsion Applications

- There have been three major areas of attempted application in propulsion:
 - Micro rocket propulsion systems
 - Micro reciprocating/rotating engine systems
 - Fuel Injection

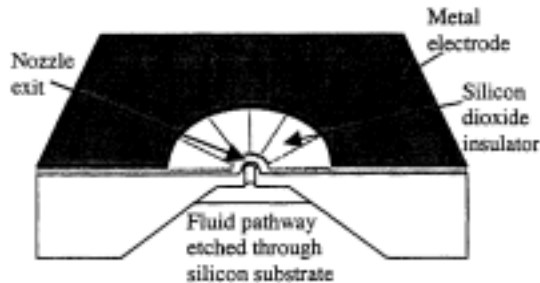
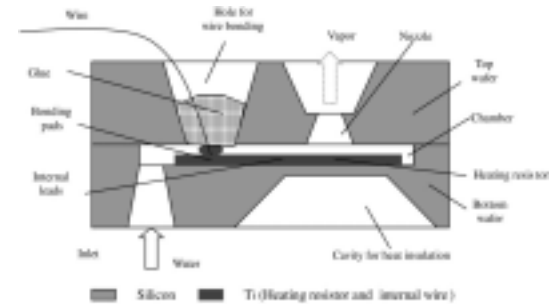




Rocket Propulsion



- Liquid
- Solid
- Gas
- Electric





Reciprocating/Rotating Engines

- Free piston engine
 - Honeywell
 - Georgia Tech
- Rotary engine
 - UC Berkeley
- Gas turbine
 - MIT

QuickTime™ and a
TIFF (Uncompressed) decompressor
are needed to see this picture.

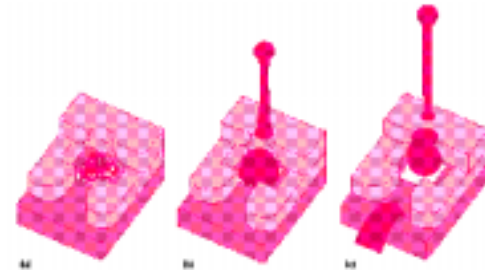
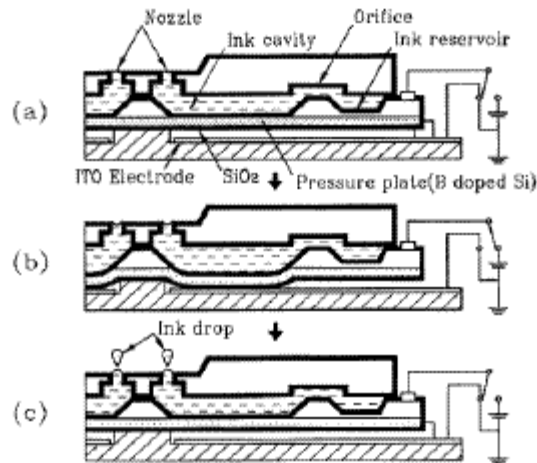
QuickTime™ and a
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Fuel Injection

- Injet Based Concepts
 - Ho was the first to explore.





Where Are (The Royal) We?

- We have made a lot of little gadgets that don't work in the real world!
- Why?
 - Poorly understood physics
 - Material compatibility issues
 - Fabrication difficulties, including dimensional stability
 - Packaging difficulties
 - Reliability





Physics

- Solid Mechanics
 - Do small scale systems behave like macro systems?
Deformations/dynamics?
 - i.e. Can I use Roark?
- Fluid Mechanics
 - Boundary conditions/Surface effects
 - i.e. Is there slip?
- Electrostatics
 - Do continuum approaches work?
 - If aspect ratio large can I use simple theory?





Material Compatibility

- Propulsion applications are often exposed to strong solvents, high temperatures and oxidizing atmospheres.
- Silicon, the master material of MEMS, is not so great in these environments.
- Adhesives are equally challenged.





Fabrication/Packaging

- Don't let anyone tell you otherwise, fabrication and packaging are Black Magic!
- All steps are critical. Small differences in etching time, sputtering voltages, adhesive composition etc. can have profound effects.
- Any wise person will keep fabrication and packaging details as trade secrets!



Reliability



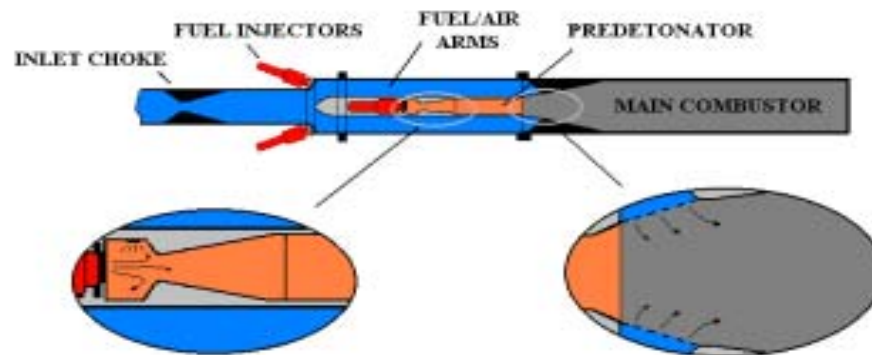
- This is a major issue for developing MEMS devices.
- Even raw supplies like wafers are often delivered with flaws or large variability in properties.
- Fabrication sensitive to procedures.





Our Case Example

- Goal - Develop a fuel injector in support of Navy air breathing PDE.
- Base design on inkjet technology.



$\Delta p < 50$ psid

SMD < 10 μm

$T_{\text{MAX}} = 500$ F

100 Hz control authority

$\phi_f = 0.5$ lbm/s

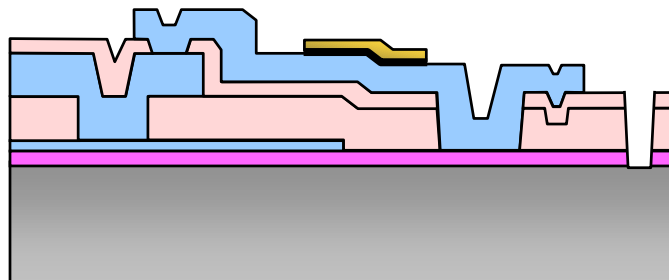
No-drip





Technical Challenges

- Adapting inkjet technologies
 - 10 μ m SMD or less
 - high mass flow
 - JP-10 fuel compatibility
- Limitations of MEMS fabrication processes



- Metal (gold)
- Polycrystalline Silicon (doped with P)
- Oxide (PSG: SiO₂ doped with P)
- Nitride (Si₃N₄)
- Crystalline Silicon

P. Kladitis, CU Boulder, 2000

- Assembly/ Bonding
- Reliability and endurance (10⁸ cycles)





Meeting the Challenges

- Physics - Analytical and multi-physics numerical modeling.
- Materials - Experiments to establish compatibility.
- Fabrication and Packaging - Simple designs and find some good people.
- Time will tell!
 - i.e make and test.





Early Assessment

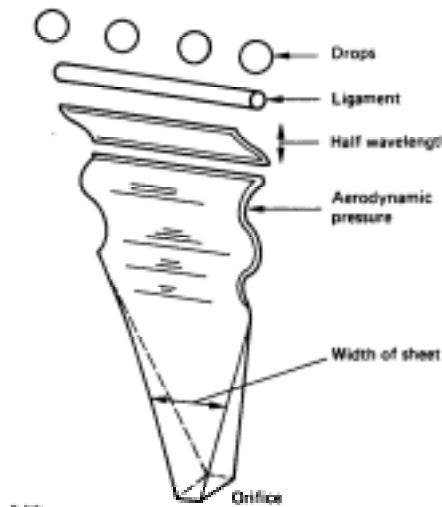
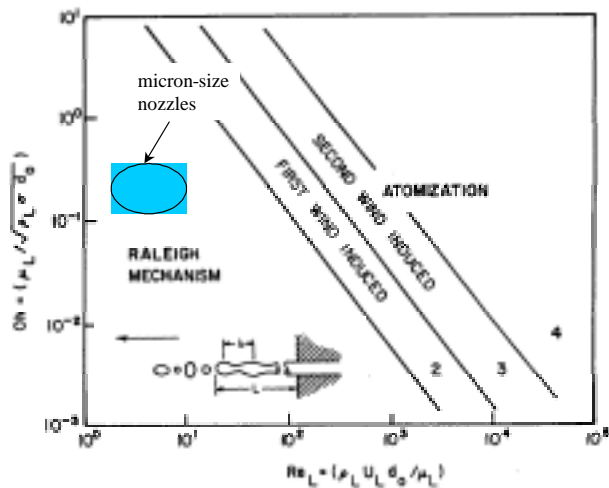
- Are small droplets possible?
- Can conventional inkjet technology be used?
- What materials are compatible with JP-10?
Are we left with materials that can be fabricated?
- What is most suitable configuration?





Small Drops?

JP-10 fluid properties not that dissimilar from inks and water.



If the holes or slots are small enough, the droplets will be small enough





Conventional Technology

- Early tests showed that adhesive and packaging materials are not compatible with JP-10.
- Not all actuation methods suitable. Thermal actuation, for example, requires far too much power.
- Fluidics not designed to operate with significant pressure drop.





Material Compatibility

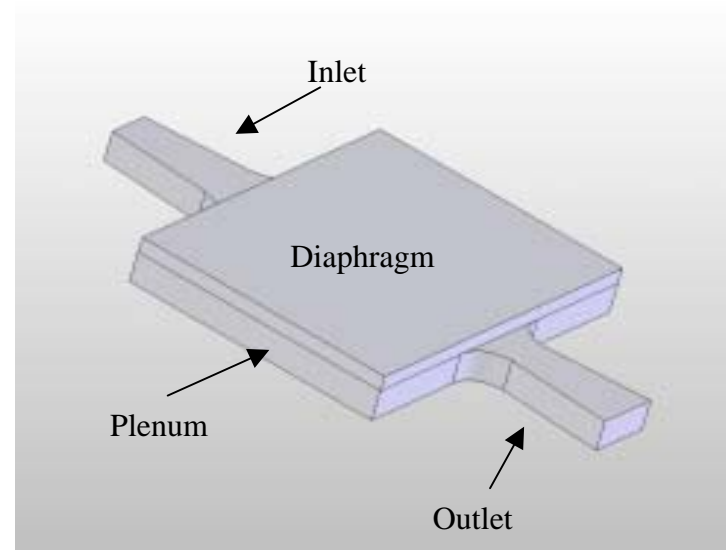
- There are materials that can handle JP-10.
- Thermal compatibility may be an issue, however, materials like SiN and SiCN can be used along with pure metals.
- There are adhesives and packaging materials that are tolerant to JP-10 and can handle thermal environment.





The Basic Design

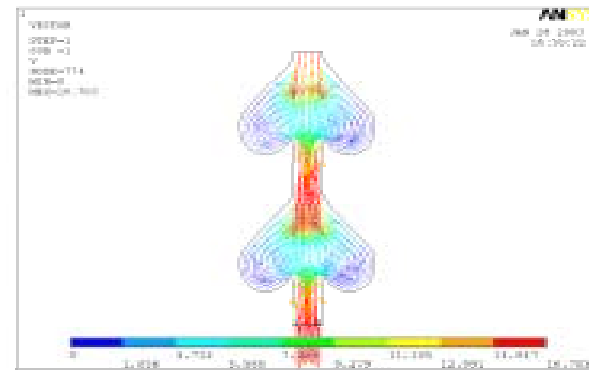
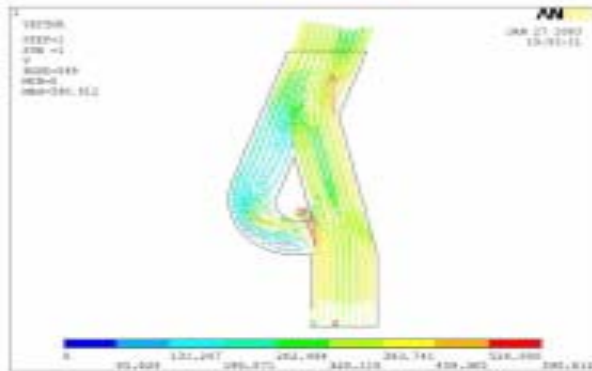
- Electrostatically actuated diaphragm pump with passive valves:
 - Electrostatic for high displacement/low power.
 - Passive valves for simplicity.





What is Important?

- Want high pump efficiency: $\eta = \frac{Q_{net}}{Q_{ideal}}$
- Valves are critical





Analysis

- Electrostatic Force

$$P = \frac{\epsilon_0 V_{app}^2}{g^2}$$

- Static Deflection

$$y_{\max} = \frac{3P(m^2 - 1)L^4}{16\pi Em^2 t}$$

- Natural Frequency

$$f_1 = \frac{13.49}{2\pi L^2} \sqrt{\frac{D}{\rho t}}$$

$$D = \frac{Et^3}{12(1-\nu^2)}$$

$$\frac{f_{1fluid}}{f_{1vac}} = \frac{1}{\left(1 + \frac{A_p}{M_p}\right)^{1/2}}$$





Analysis

- Pressure Drop (Nozzle/Diffuser)

$$\Delta p_{N,D} = K_{N,D} \rho \frac{V^2}{2} \quad \eta = \frac{K_N}{K_D}$$

- Net Flow Rate

$$Q_p = \frac{V_0 \omega}{\pi} \left(\frac{\eta^{1/2} - 1}{\eta^{1/2} + 1} \right)$$

- Question: How well do these work?





Numerical Methods

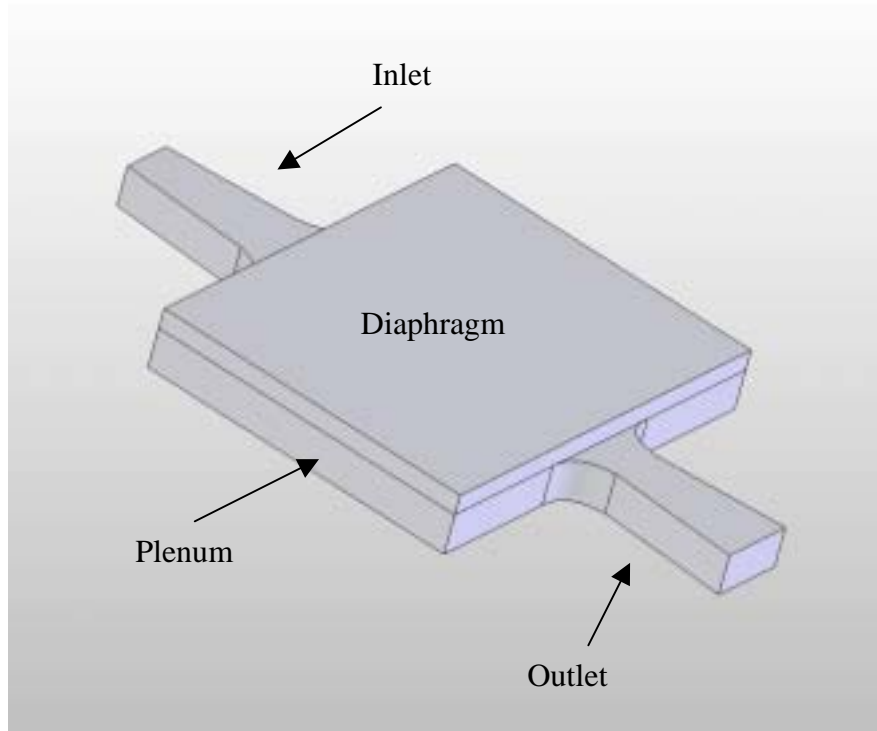
- ANSYS Multi-physics finite element code is used to carry out simulation:
 - Weak sequential algorithm to couple structural and fluid dynamics,
 - Arbitrary Lagrangian-Eulerian formulation solves for the fluid flow with moving boundaries,
 - Fluid dynamics is solved using ANSYS FLOTRAN (Flow treated as incompressible.)





Example

Time Dependent 3-D Simulation



$$L_{\text{diaph}} = 1 \text{ mm}$$

$$t_{\text{diaph}} = 50 \text{ } \mu\text{m}$$

$$t_{\text{plenum}} = 100 \text{ } \mu\text{m}$$

$$t_{\text{passages}} = 100 \text{ } \mu\text{m}$$

$$L_{\text{passages}} = 0.33 \text{ mm}$$

$$W_{\text{inpassages}} = 66.7 \text{ } \mu\text{m}$$

$$\alpha_{\text{valve}} = 5 \text{ degrees}$$

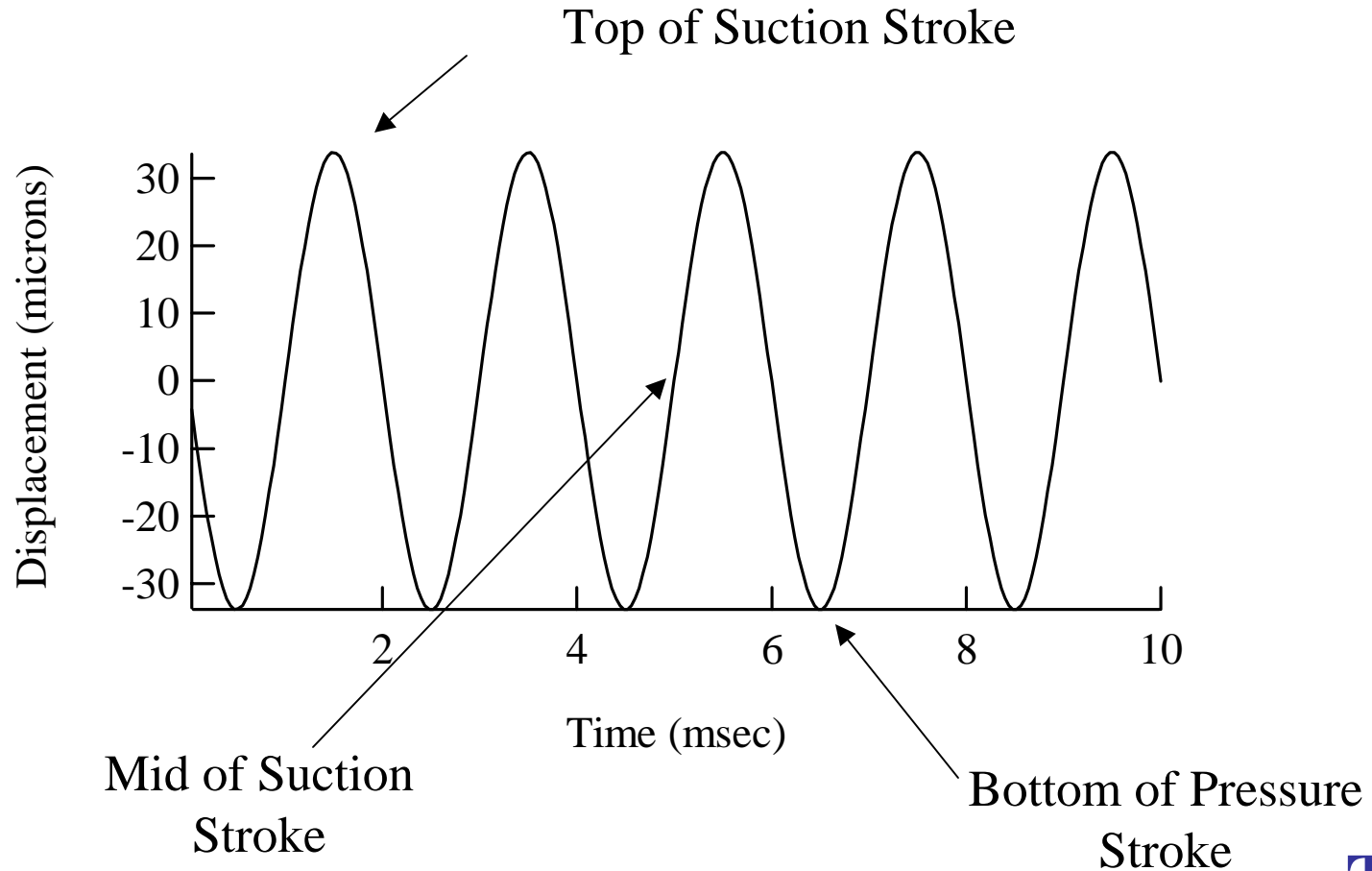
Simulation uses vertical symmetry plane

Calculations for 100-900 Hz





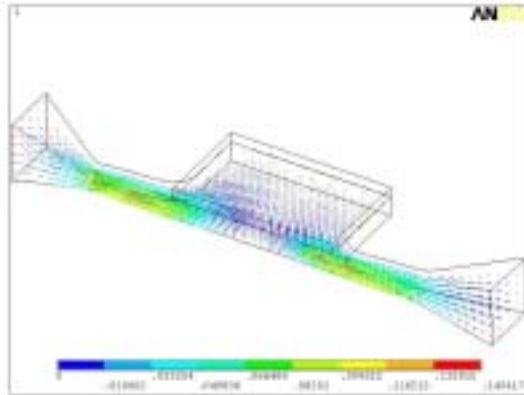
Displacement 500 Hz



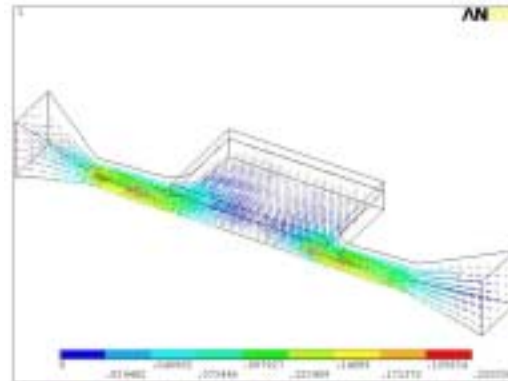
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Flow Field

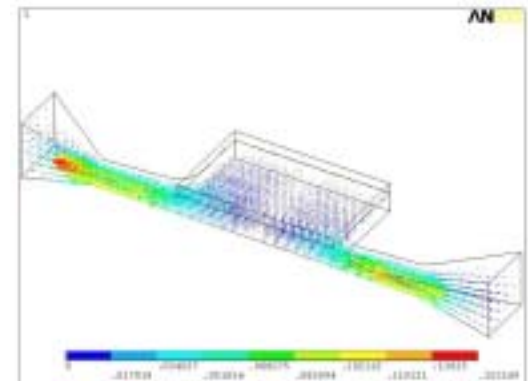


Top of Suction
Stroke

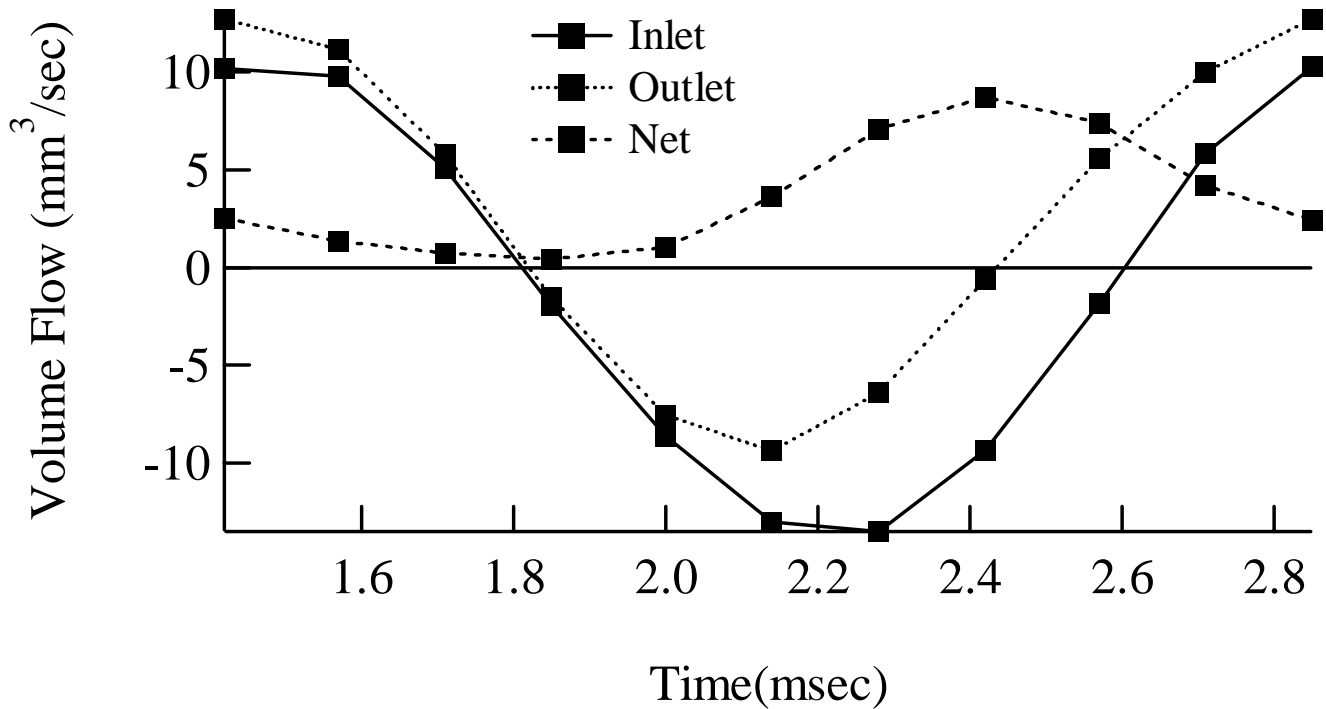


Mid of Suction
Stroke

Bottom of Pressure
Stroke

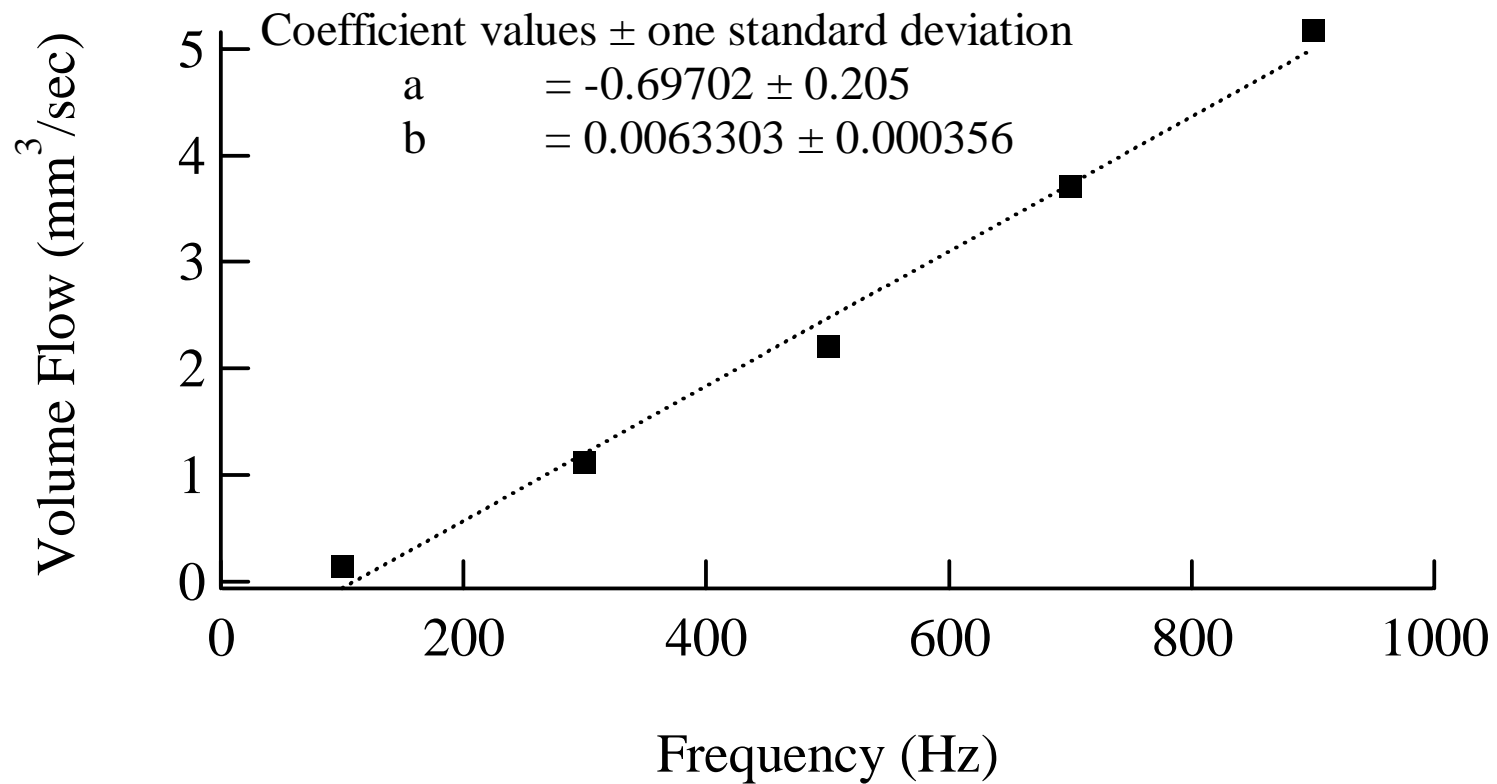


Flow Rates 700 Hz





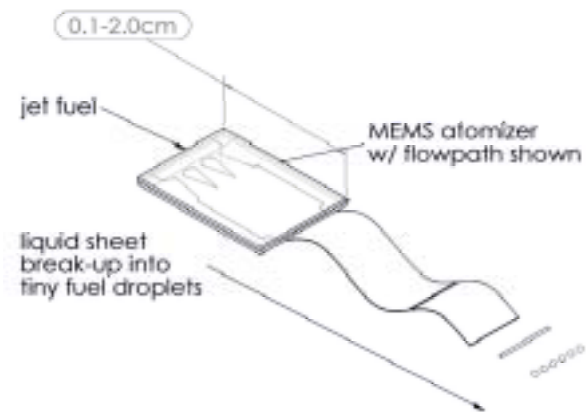
Net Flow Rate





Further Design and Physics Issues

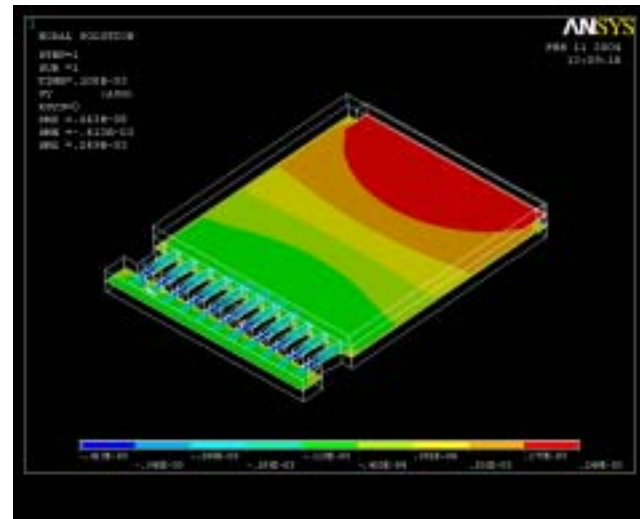
- Physics
 - Nonlinear diaphragm behavior.
 - Accuracy of simple electrostatic models.
- Design
 - Maximize flow rate.
 - Slot designs
 - Larger size





Full Simulations of 1 cm Devices

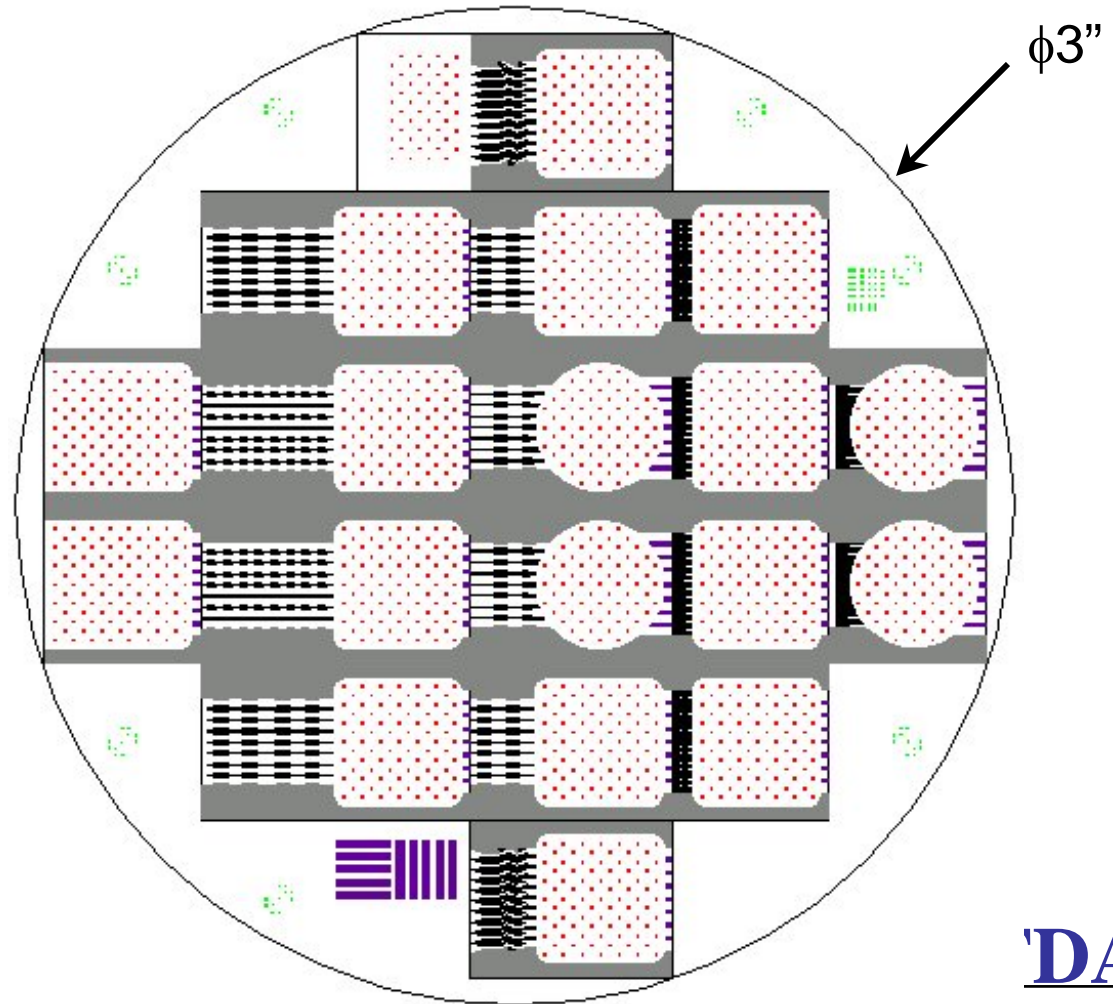
- Full manifolding
- Different valve configurations
- Non-linear where required
- Electrostatics





Fabrication

Layered design
with diaphragm
sandwiched
between two
similar substrates



QuickTime™ and a
H264 (13) (compressed) decompressor
are needed to see this picture.



Packaging





Summary

- MEMS devices show great promise.
- Task is to translate promise into practice.
- Must consider larger range of problems than in conventional technology.

